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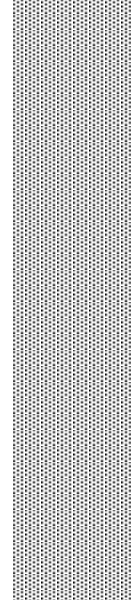
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۱. Contiguity
۲. Less-developed Countries
۳. Economic Convergence
۴. Spillover Effects

(OIC)

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- ۱. Organization of Islamic Conference
- ۲. Spatial Econometrics
- ۳. Solow-Swan Growth Model

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$$y = Ak^\alpha$$

• $\alpha < 1$

y

k

A >

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$$k' = s.f(k) - (n+\delta).k$$

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\. R. J. Barro and X. Sala-I-Martin (1995)

$$k_{s+1} = (1-\delta)k_s + s f(k_s)$$

$$\beta (k_{s+1})^\sigma = \beta (k_s)^\sigma$$

1. Steady State

2. Absolute Convergence Hypothesis

y ...

β

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$$L_n(y_t) = (1 - e^{-\beta t}) L_n(y^*) + e^{-\beta t} L_n(y_0) \quad (1)$$

β ... y_0 ... y^*

(1)

:

$$L_n\left(\frac{Y_{it+1}}{Y_i}\right) = \alpha + \beta L_n Y_{it} + \varepsilon_i \quad (2)$$

$$L_n\left(\frac{Y_{it+1}}{Y_i}\right) - \beta L_n Y_{it} = \alpha + \varepsilon_i$$

β

: (3) β k

$$\theta = \frac{L_n(\beta + 1)}{-k} \quad (4)$$

1. Conditional Convergence Hypothesis

2. Convergence speed

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k

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Akbari and Farahmand (۲۰۰۴)

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۱. Spatial Dependence

۲. Spatial Heteroscedasticity

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(j≠i) j (i)

$y_i = f(y_j), i = 1, \dots, n, i \neq j$ ()

y

$y_i = f_i (X_i \beta_i + \epsilon_i)$ ()

X_i, i

y_i

: (SAR)

1. J. P. Le Sage (1995)

.2

2. Spatial Lag Model

3. Spatial lag of the dependent Variable

$$W_{ij} = \begin{cases} 1 & \text{if } i \text{ and } j \text{ are neighbors} \\ 0 & \text{otherwise} \end{cases}$$

$n \times n$

$$y = \rho W y + X \beta + \epsilon \quad (1)$$

$$(I - \rho W) y = X \beta + \epsilon$$

$$y = (I - \rho W)^{-1} X \beta + (I - \rho W)^{-1} \epsilon \quad (2)$$

OLS

- 1. Spatial Smoother
- 2. Spatial Weight Matrix
- 3. Mixed Spatial Autoregressive – Regressive Model

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: (SEM)

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$$y = X\beta + \epsilon, \quad ()$$

$$\epsilon = \lambda w\epsilon + u$$

λ

:

$$y = X\beta + (I - \lambda w)^{-1} u \quad ()$$

$$(C) \quad (I)$$

$$(C) \quad (I)$$

:

$$I = N / S \cdot \sum_i \sum_j w_{ij} (y_j - \mu) \cdot (y_i - \mu) / \sum_i (y_i - \mu)^2 \quad ()$$

$$C = (N - 1) / \sum_i (y_i - \mu)^2 \cdot \sum_i \sum_j w_{ij} \cdot (y_i - y_j)^2 / \sum_i (y_i - \mu)^2 \quad ()$$

$$(I) \quad N \quad \mu \quad y_i \quad C \quad I$$

$$(I) \quad S \quad /N$$

- 1. Spatial Error Model
- 2. L. Anselin (1999)
- 3. Moran- I Test
- 4. Geary-C Test
- 5. Moran Scatter plot

(C)

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(

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$$L_n \left(\frac{Y_{it+k}}{Y_{it}} \right) = \alpha + \rho L_n \left(\frac{Y_{it+k}}{Y_{it}} \right) + \beta L_n Y_{it} + \varepsilon \quad ()$$

$$L_n \left(\frac{Y_{it+k}}{Y_{it}} \right) = \alpha + \beta L_n Y_{it} + \varepsilon \quad ()$$

$$\varepsilon_{it} = \lambda w \varepsilon_{it} + u \quad ()$$

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¶. S. J. Rey & B. D. Montoury (1999)

¶. E. Vaya et.al (1999)

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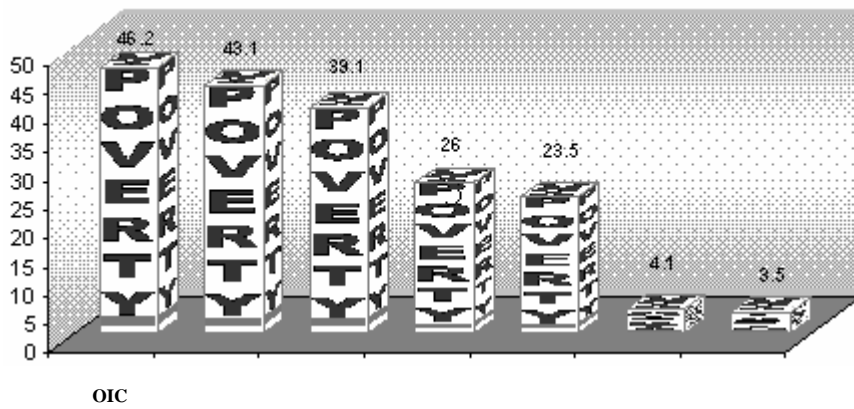
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۲. The statistical, Economic and Social Research and Training Center for Islamic Countries (SESRTCIC), (۲۰۰۰)

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SpaceStat

(OLS)

(ML)

OIC

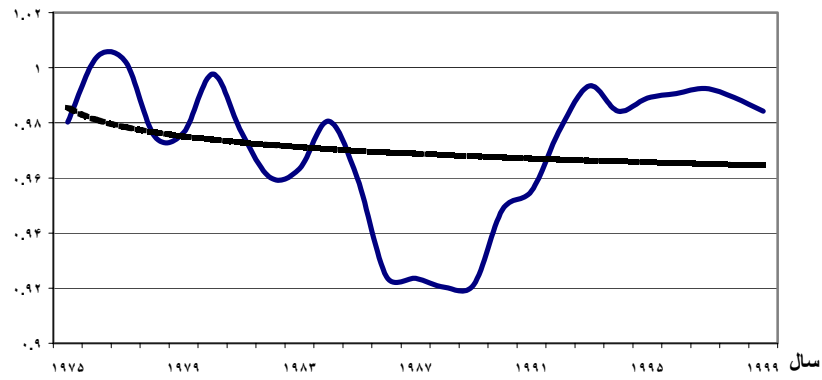
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- 1. Maximum Likelihood
- 2. O. Gurler (2000)

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β

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$$\hat{G}_y = \frac{1}{L_n} - \frac{1}{L_n} L_n y^{\Delta} \quad ()$$

$$R^2 = \frac{1}{L_n}$$

\hat{G}_y

$$L_n \left(\frac{Y_{it+k}}{Y_{it}} \right)$$

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$L_n y^{\Delta}$

\hat{G}_y

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y ...

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OLS

(C) (I) (\hat{y})
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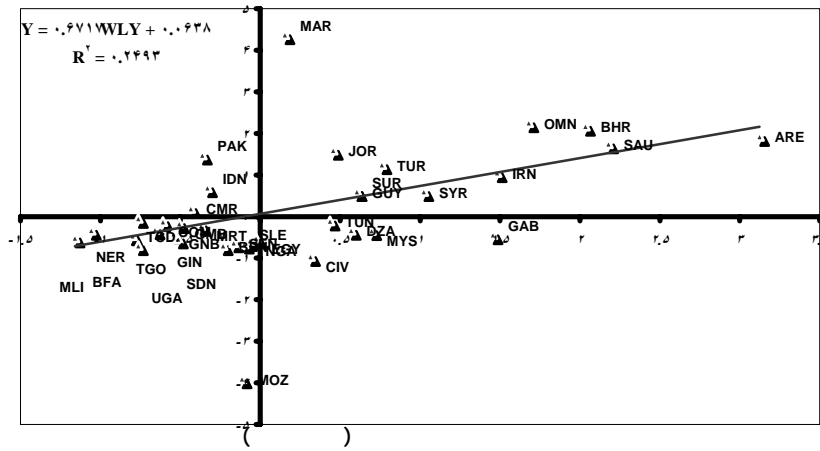
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/	/	/	/	/	(I)
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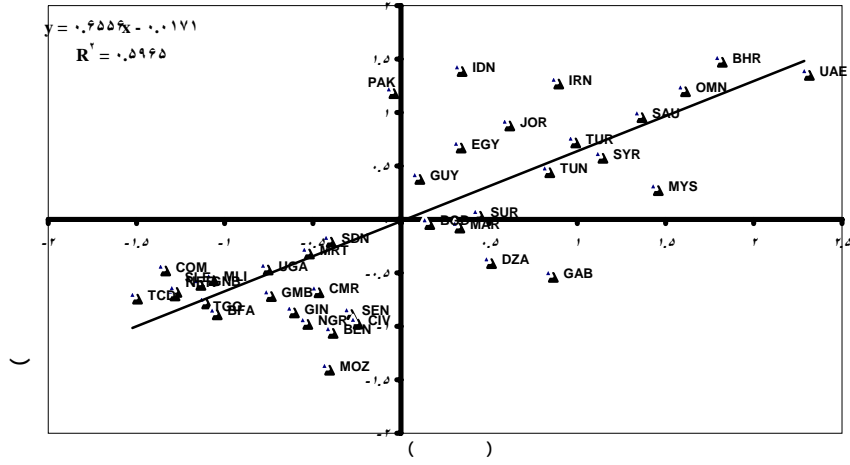


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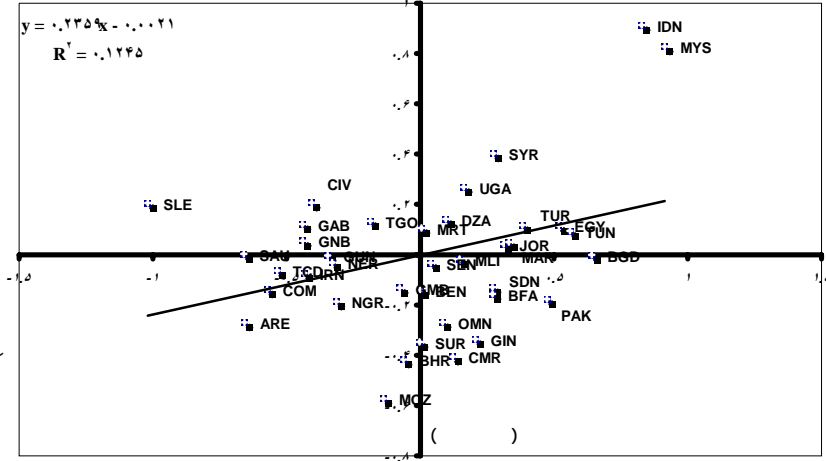
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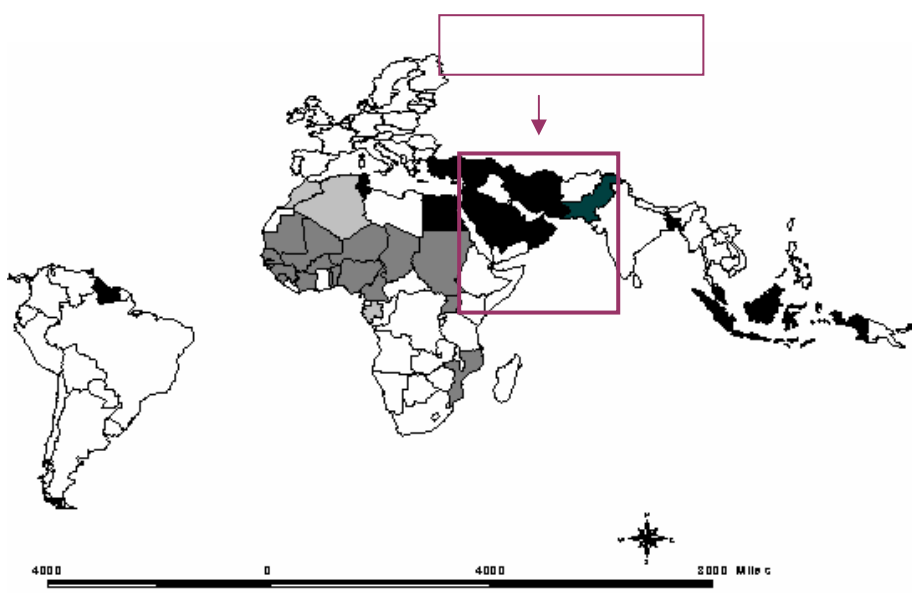
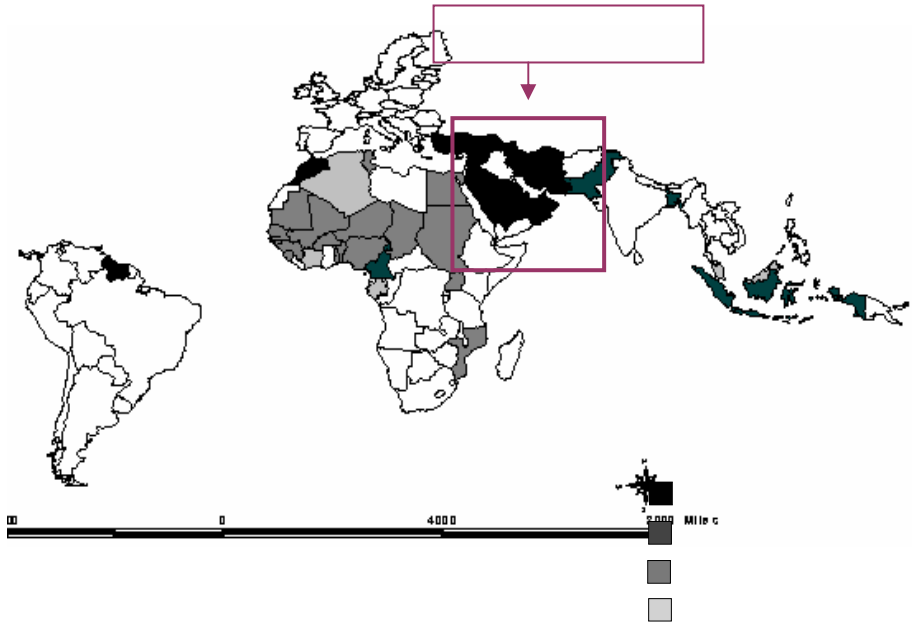
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/	/	LM (Error)	
/	/	Robust LM (Error)	
/	/	LM (Lag)	
/	/	Robust LM (Lag)	
/	/	LM (SARMA)	

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(SEM SAR)

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) (SEM)

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AIC

OLS

	α	β	θ	Spatial Effect	R^2	AIC	LR
OLS	/ (/)	/ (/)	/		/	/	
SAR	/ (/)	/ (/)	/	$\rho =$ / (/)	/	/	/ (/)
SEM	/ (/)	/ (/)	/	$\lambda =$ / (/)	/	/	/ ()

: β : α
 : λ : θ
 :SEM :SAR :OLS
 :LR :AIC :R^۲

SEM ()

/

/

/ λ

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SEM SAR (

۱. $e^{-\lambda t} = 1/\lambda \rightarrow t = 1/\lambda$, $e^{-\lambda t} = 1/\lambda \rightarrow t = 1/\lambda$

Barro & Sala-i-Martin (۱۹۹۵)

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(/) / /

(LY_{v0})

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	α	β	θ	Spatial Effect	R^2	AIC	LR
OLS	/ (/)	/ (/)	/		/	/	
SAR	/ (/)	/ (/)	/	$\rho =$ / (/)	/	/	/ (/)
SEM	/ (/)	/ (/)	/	$\lambda =$ / (/)	/	/	/ (/)

: β : α

: λ : ρ : θ

:SEM :SAR :OLS

:LR :AIC :R²

/

Robust LM

/ / / SEM / SAR
(SEM SAR)

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SEM SAR

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□	۰ - ۰,۱۳۸
□	۰,۱۳۸ - ۰,۳۱۴
□	۰,۳۱۴ - ۰,۴۷۹
□	۰,۴۷۹ - ۱,۰۲۵
□	۱,۰۲۵ - ۱,۸۱۴
□	۱,۸۱۴ - ۴,۱۶
□	۴,۱۶ - ۷,۷۳۳





4000 0 4000 8000 Miles

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(/)

$\lambda = /$

($\theta = /$)

"() " () .

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(OIC :)

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